

## **LR1120**

## **Low Power Wi-Fi® / GNSS Scanner & Multi-band LoRa® Transceiver**



The LR1120 is an ultra-low power, long range multi-band LoRa transceiver targeting geolocation applications. It integrates a long range LoRa® modem, a multi-constellation global navigation satellite system (GNSS) scanner, and a passive Wi-Fi® Access Point address scanner.

For LPWAN use cases, the LR1120 supports LoRa® and (G)FSK modulation on both sub-GHz and 2.4 GHz bands. It also supports Long Range Frequency Hopping Spread Spectrum (LR-FHSS) on sub-GHz and 2.4 GHz ISM bands.

The LR1120 complies with the physical layer requirements of the LoRa Alliance® LoRaWAN® specification, while remaining configurable to meet different application requirements and proprietary protocols.

The radio is suitable for systems targeting compliance with radio regulations including but not limited to ETSI EN 300 220, FCC CFR 47 Part 15, and Chinese regulatory requirements.

Besides world-wide sub-GHz and 2.4 GHz communication capabilities, the very-low-power multi-band front-end is capable of acquiring several signals of opportunity used for geolocation:

- **•** 802.11b/g/n Wi-Fi Access Point MAC addresses
- **•** GNSS (GPS, BeiDou, geostationary) satellite signals

Acquired information is transmitted over an LPWAN network to a geolocation server. The geolocation server analyses the signal information and calculates the LR1120's position with data from a geolocation database, enabling a valuable balance between low power and performance.



### **Disclaimer**

**Long Range-Frequency Hopping Spread Spectrum (LR-FHSS) is a high link-budget, high-performance technology combining the benefits of a modulation employing low energy per bit and advanced frequency hopping schemes to achieve improved coexistence, spectral efficiency and sensitivity. Semtech Corp. holds patents directed to aspects of the LR-FHSS technology.**

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## **Ordering Information**



QFN32 Package, Pb-free, Halogen free, RoHS/WEEE compliant product.

### **Revision History**



1. Use Case and Version concepts are defined in the LR1120 User Manual, see the GetVersion command.

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# <span id="page-4-0"></span>**1. System Description**

# <span id="page-4-1"></span>**1.1 Simplified Block Diagram**

**Figure 1-1: LR1120 Simplified Block Diagram**



## <span id="page-5-0"></span>**1.2 Overview**

## <span id="page-5-1"></span>**1.2.1 Low-Power High-Sensitivity LoRa®/(G)FSK Half-Duplex RF Transceiver**

- **•** Worldwide frequency bands support in the range 150 960 MHz (sub-GHz) and 2.4 GHz ISM band.
- **•** Low Noise Figure modes for enhanced LoRa/ (G) FSK sensitivity (differential input pins RFI\_P/N\_LF0)
- **•** High power PA path +22 dBm (pin RFO\_HP\_LF) and High efficiency PA path +15 dBm (pin RFO\_LP\_LF) for sub-GHz
- **•** High frequency PA path +13 dBm (pin RFIO\_HF) for 2.4 GHz ISM band, matched to 50 Ohm impedance, reducing the overall Bill Of Materials cost
- **•** Integrated PA regulator supply selector to simplify dual power +15/+22 dBm with a single board implementation
- **•** Able to support world-wide multi-region BOM, the circuit adapts to satisfy regulatory limits
- **•** Fully compatible with the SX1261/2/8 family and the LoRaWAN® standard, defined by the LoRa Alliance
- **•** LR-FHSS Transmitter, with intra-packet hopping capability

## <span id="page-5-2"></span>**1.2.2 Multi-Purpose Radio Front-End**

- **•** 150 2500 MHz continuous frequency synthesizer range (2400 MHz 2500 MHz operation on input/output pin RFIO\_HF)
- **•** GPS/ BeiDou scanning (differential input pins RFI\_P/N\_LF1)
- **•** Wi-Fi® passive scanning (using input/output pin RFIO\_HF)
- **•** Digital baseband

## <span id="page-5-3"></span>**1.2.3 Power Management**

- **•** Two forms of voltage regulation (DC-DC or linear regulator, LDO) are available depending upon the design priorities of the application. DC-DC usage is recommended for power efficient operation at the cost of an extra inductor.
- **•** Power On Reset (POR), Brown-out detection and Low Battery indication are supported
- **•** Battery voltage measurement

## <span id="page-5-4"></span>**1.2.4 Clock Sources**

- **•** 32.768 kHz Low Frequency (LF) internal RC oscillator, optionally used by the circuit Real Time Clock (RTC)
- **•** 32.768 kHz LF crystal oscillator (XOSC), used for the RTC. An external 32.768 kHz reference from a host, applied to pin DIO11, is also possible.
- **•** 32 MHz HF RC (HFRC) oscillator allowing configuration of the device without the need to start the main crystal oscillator
- **•** 32 MHz HF crystal oscillator, HFXOSC, used for radio operation and to calibrate the frequency error of the internal RC oscillators
- **•** 32 MHz TCXO can be used to supply the main clock to the circuit, its power supply being integrated on-chip by REG\_TCXO, on pin VTCXO. The circuit is able to boot when a TCXO is connected instead of a 32 MHz crystal, however all start-up (POR) calibrations are skipped. The host processor should program the TCXO configuration and re-launch the calibrations before further usage of the chip. The use of a TCXO is mandatory for GNSS scanning operations.

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## <span id="page-6-0"></span>**1.2.5 Digital Subsystem**

The circuit on-boards power-efficient functionalities, with sufficient hardware resources to implement a wide range of applications:

- **•** Logic to control chip modes, radio front-end, power management and digital interfaces
- **•** RAM partially retained during sleep mode
- **•** Non-volatile memory (NVM)
- **•** Slave serial peripheral interface (SPI)
- **•** DIO0 used as "BUSY" indicator, indicating that the internal MCU cannot receive any commands from the host controller
- **•** Hardware de-bounce and event detection (IOCD)
- **•** Low-power real-time counter (RTC) and watch-dog timer (WDG)
- **•** LoRa, (G)FSK, modems compatible with the SX126x and SX127x product families in sub-GHz bands
- **•** LoRa, (G)FSK, modems compatible with the SX128x product families in the 2.4 GHz ISM band
- **•** Long Range FHSS in transmit mode, with intra-packet hopping capability

## <span id="page-6-1"></span>**1.2.6 Cryptographic Engine**

- **•** Hardware support for AES-128 encryption/decryption based algorithms
- **•** Handling device parameters such as DevEUI and JoinEUI, as defined by the LoRa Alliance®
- **•** Protects confidential information such as encryption keys against unauthorized access
- **•** Stores NwkKey, AppKey, as defined in the LoRaWAN® standard

# <span id="page-7-0"></span>**2. Pin Connection**

### **Table 2-1: LR1120 Pinout**



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# <span id="page-9-1"></span><span id="page-9-0"></span>**3.1 Absolute Maximum Ratings**

Stresses above the values listed below may cause permanent device failure. Exposure to absolute maximum ratings for extended periods may affect device reliability, reducing product life time.



#### **Table 3-1: Absolute Maximum Ratings**

# <span id="page-9-2"></span>**3.2 Operating Range**

Operating ranges define the limits for functional operation and parametric characteristics of the device as described in this section. Functionality outside these limits is not guaranteed.

#### **Table 3-2: Operating Range**



# <span id="page-10-0"></span>**3.3 ESD and Latch-up**

The LR1120 is a high performance radio frequency device presenting high ESD and latch-up robustness on all pins. The chip should be handled with all the necessary ESD precautions to avoid any permanent damage.





# <span id="page-10-1"></span>**3.4 Electrical Specifications**

The tables below give the electrical specifications of the LR1120 transceiver under the following conditions, unless otherwise specified:

- **•** VBAT\_RF = VBAT = 3.3 V, Temperature = 25 °C, FXOSC = 32 MHz, crystal oscillator,
- **•** FRF = 915/869 MHz for sub-GHz path FSK and LoRa®,
- **•** FRF = 1.57542 GHz for the GNSS path,
- **•** FRF = 2.45 GHz for the RFIO\_HF path,
- **•** All RF impedances on the sub-GHz and RFIO\_HF path are matched using multi-band reference design, transmit mode output power defined in 50  $\Omega$  load, RxBoosted = 1 for LoRa and FSK, differential use of the LNAs (receiver gain levels are referenced in the device's User Manual),
- **•** FSK Bit Error Rate (BER) = 0.1%, 2-level FSK modulation without pre-filtering, BR = 4.8 kb/s, FDA = 5 kHz, BWF = 20 kHz,
- **•** LoRa Packet Error Rate (PER) = 1%, BWL= 125 kHz, packet of 64 bytes, preamble of 8 symbols, error correction code CR=4/5, CRC on payload enabled, explicit header, sub-GHz frequency range,
- **•** GNSS and Wi-Fi sensitivity given for 10% PER,
	- Wi-Fi b, MPDU size of 272 bits, or 34 Bytes
	- Wi-Fi g/n, MPDU size of 288 bits, or 36 Bytes
- **•** Blocking Immunity, ACR, and co-channel rejection are given for a single tone interferer and referenced to sensitivity +3 dB, blocking tests are performed with unmodulated interferer,
- **•** All power consumption numbers are given with XTAL mode used, the consumption of the TCXO has to be added,
- **•** All power consumption numbers are given without considering the external LNA on the GNSS path,
- **•** All receiver BW are expressed as **Double SideBand (DSB)** throughout this document.

## <span id="page-11-0"></span>**3.4.1 Power Consumption**

The tables below give the total consumptions of all blocks in the specified modes of the circuit.

**Table 3-4: Basic Modes Power Consumption**

<b>Symbol</b>	<b>Description</b>	<b>Conditions</b>	Min	<b>Typ</b>	Max	Unit
<b>IDDPDN</b>	Supply current in power down mode			0.8	$\overline{\phantom{0}}$	μA
<b>IDDSL3</b>	Supply current in SLEEP mode, no RTC	8 kB RAM retained		1.6	$\overline{\phantom{0}}$	μA
<b>IDDSL1</b>	Supply current in SLEEP mode	No RAM retained		1.6	$\qquad \qquad \blacksquare$	μA
<b>IDDSL3A</b>	LFRC (32 kHz) based RTC	8 kB RAM retained		1.85	-	μA
<b>IDDSL2</b>	Supply current in SLEEP mode	No RAM retained		1.5	$\overline{\phantom{a}}$	μA
<b>IDDSL4A</b>	LFXOSC (32 kHz) based RTC	8 kB RAM retained		1.75	$\overline{\phantom{0}}$	μA
<b>IDDSBRLD</b>	Supply current in STBY_RC	HFRC (32 MHz) ON, LDO,		1.25	$\overline{\phantom{a}}$	mA
		System clock 16 MHz				
<b>IDDSBXLD</b>	Supply current in STBY_XOSC	HFXOSC ON, LDO		1.3	$\overline{\phantom{a}}$	mA
<b>IDDSBXDC</b>		HFXOSC ON, DC-DC		1.1	$\overline{\phantom{a}}$	mA
<b>IDDFSDC</b>	Supply current in Synthesizer mode	DC-DC, system clock 32 MHz		2.85	$\qquad \qquad \blacksquare$	mA

#### **Table 3-5: Receive Mode Power Consumption, DC-DC mode used**



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### **Table 3-6: Transmit Mode Power Consumption1**

1. Using optimized settings described in the LR1120 User Manual.

2. DC-DC mode of the LDO/DC-DC combo is used to supply the entire circuit.

3. Battery used to supply the PA, and DC-DC used to supply the rest of the circuit.

#### **Table 3-7: Wi-Fi Passive Scanning Duration1**



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1. Demodulation time given as the calculated average time over 100 packets

2. Preamble detection phase depends significantly on the traffic in the scanner channel, beacon are sent every 102.4 ms

3. Time depends on beacon size

4. Time depends on beacon size

#### **Table 3-8: Wi-Fi Passive Scanning Average Energy Consumption, DC-DC mode used**



#### <span id="page-13-0"></span>**Table 3-9: GNSS Scanning Duration**



1. Indoor conditions, 0 SV detected



## <span id="page-14-0"></span>**Table 3-10: GNSS Scanning Energy Consumption, DC-DC mode Used<sup>1</sup>**

1. It takes into account only the energy needed by the LR1120 to acquire the signals of opportunity and does not include any uplink/ downlink communication to transmit the information to the servers, or receiver Almanac /Ephemeris data.

## <span id="page-15-0"></span>**3.4.2 General Specifications**





1. Maximum bit rate is assumed to scale with the RF frequency; example 300 kb/s in the 869/915 MHz frequency bands and only 50 kb/s @150 MHz 2. For RF frequencies below 300 MHz, the LoRa signal BW is limited to maximum 250 kHz, the data rate being reduced accordingly

## <span id="page-16-0"></span>**3.4.3 Receiver**



#### **Table 3-12: Receiver Specifications, Sub-GHz Bands**



### **Table 3-12: Receiver Specifications, Sub-GHz Bands (Continued)**

1. LoRa operation is on the 150 - 960 MHz band

2. Single ended impedance

3. Phase Noise specifications are given for the recommended PLL bandwidth to be used for the specific modulation/ bit rate

4. Phase Noise is not constant over frequency, the topology of VCO + DIV used, for two frequencies close to each other, the phase noise could change significantly; the specification covers the worse value



### **Table 3-13: Receiver Specifications, RFIO-HF Path**



### **Table 3-13: Receiver Specifications, RFIO-HF Path (Continued)**

### **Table 3-14: Receiver Specifications, GNSS Scanner1**



1. All sensitivity numbers are given using the external LNA listed in the reference design. 2. Single ended impedance.

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#### **Table 3-15: Receiver Specifications, Wi-Fi Passive Scanner**

1. 2.4 GHz Wi-Fi n only, mixed mode

## <span id="page-21-0"></span>**3.4.4 Transmitter**



#### **Table 3-16: Transmitter Specifications, sub-GHz Path**

### **Table 3-17: Transmitter Specifications, RFIO\_HF Path**



# <span id="page-22-0"></span>**3.5 Reference Oscillator**

#### **Table 3-18: 32 MHz Crystal Specifications**



#### **Table 3-19: 32 MHz TCXO Regulator Specifications**



### **Table 3-20: 32 kHz Crystal Specifications**



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# <span id="page-23-0"></span>**3.6 Digital I/O, Flash Memory, & Interface Specifications**

## <span id="page-23-1"></span>**3.6.1 Digital I/O Specifications**

#### **Table 3-21: Digital I/O and NRESET Specifications**



## <span id="page-23-2"></span>**3.6.2 Flash Memory Specifications**

The LR1120 embeds a Flash memory to store the internal firmware, application configuration data, and security keys.

#### **Table 3-22: Flash Memory Specifications**



## <span id="page-23-3"></span>**3.6.3 SPI Interface**

The SPI interface gives access to the configuration register via a synchronous full-duplex protocol corresponding to CPOL = 0 and CPHA = 0 in Motorola/Freescale nomenclature. Only the slave side is implemented. A transfer is always started by a falling edge of NSS. MISO is high impedance when NSS is high. The SPI runs on the external SCK signal to allow high speed operation up to 16 MHz.

All timings in the following table are given for a maximum load capatitance of 10 pF.

#### **Table 3-23: SPI Timing Requirements**



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# <span id="page-24-0"></span>**4. Application Information**

# <span id="page-24-1"></span>**4.1 Signals of Opportunity Scanning Modes**

This section gives more insight into the scanning modes available in the LR1120.

## <span id="page-24-2"></span>**4.1.1 Wi-Fi Passive Scanning**

The LR1120 is able to discover the Wi-Fi b/g/n access points available in the vicinity of the device, and extract MAC addresses allowing to geolocate the device. The objective is to obtain at least 2 MAC addresses, which are sent to an online Wi-Fi lookup service that determines the position of the device.

To be power efficient, only a small portion of the Wi-Fi packets containing the MAC address information are captured and demodulated.

#### **Figure 4-1: Wi-Fi Passive Scanning Principle**



The Wi-Fi passive scanning is composed of a sequence of three phases: preamble search, capture and demodulation, providing one MAC address, if any are found. To obtain additional MAC addresses the three-phase sequence has to be repeated. To preserve power, the RF front-end is turned off during the demodulation phase. The MAC address is the only mandatory information required to find the location of the device. The associated signal level, RSSI, is also extracted and can be sent optionally to the solver to enhance the accuracy. The Wi-Fi passive scanning implemented in the LR1120 can also extract the country code information of an access point, contained in the beacon or probe response.

A single Wi-Fi passive scan spans three phases:

- 1. The preamble search phase, the device stays in RX mode until the start of a preamble is detected
- 2. The capture phase, the device captures the part of the packet containing the required information
- 3. The demodulation phase, the required information is demodulated





The preamble search duration depends on the traffic in the channel.

- **•** For busy channels, a preamble will quickly be detected.
- **•** For channels where only an AP signal is present, and little traffic is generated, the preamble search can be as long as the beacon interval set for that specific AP (nominally set to 102.4 ms).

## <span id="page-26-0"></span>**4.1.2 GNSS Scanning**

The LR1120 features a fast and low-power GNSS scanner. The device captures a short portion of the signal broadcast by the GNSS satellites and extracts the information required to calculate the device position - the pseudo-ranges. This information is aggregated into a NAV message which can be sent to a solver to compute the device position.



#### **Figure 4-3: GNSS Scanning Principle, Assisted Mode**

The LR1120's GNSS scanner hardware can support the following constellations:

- **•** GPS L1 + GPS geostationary SBAS: EGNOS and WAAS
- **•** BeiDou B1 + BeiDou geostationary GEO/IGSO

The search for space vehicles is a three-dimensional search challenge: the satellite ID, the frequency offset due to Doppler shift, and the code phase are unknown. Providing assistance information to the LR1120 will minimize the search space, reducing the capture time and the energy spent. To accelerate the detection of SVs, the following assistance parameters can be provided to the LR1120:

- **•** A rough estimate of the initial position of the device
- **•** The current time
- **•** The frequency reference error to be compensated
- **•** A recent version of the Almanac, required to estimate the position of the visible SVs, at the time and location of the scan

All these parameters contribute to the total error of the Doppler estimation for each satellite:

- **•** 200 km error on the initial position is equivalent to 200 Hz increase of the frequency search space
- **•** +/-30 seconds of error on the time estimation are equivalent to 20 Hz increase of the frequency search space
- **•** 0.1 ppm frequency reference error is equivalent to 150 Hz increase of the frequency search space
- **•** Every month of age of the Almanac contributes to 62 Hz increase of the frequency search space

Once a short period of the satellite broadcast signal is captured, the detection of space vehicles on the LR1120 is done in two main phases:

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- **•** a faster search of the available SVs received by the device with a strong signal
- **•** a more in-depth search of the available SVs received by the device with a weak signal

Besides providing the pseudo-ranges of those satellites received with strong signal, the first phase also estimates the device's frequency offset and defines the frequency search space for the second phase.

The second phase implies a search centred on the frequency offset resulting from the Doppler error and the frequency reference error on the device. With the best assistance information, the search can be limited to a window of only 125 Hz. With an assistance information less precise, for instance if the ephemeris data is out of date, the search window is extended in steps of +/- 125 Hz, increasing the search time and the energy consumption. See [Table](#page-13-0) 3-9 and [Table](#page-14-0) 3-10 for details.

The LR1120 can take into account Almanac information to speed up the GNSS signal processing step. The Almanac parameters contain coarse orbital parameters which describe the Space Vehicles motion in space. Together with a coarse estimate of time and position, the Almanac can be used to exclude irrelevant space vehicles and reduce the search window for the Doppler error search.

All assistance information transferred to the LR1120 is tailored for an LPWAN use-case, which mean low-throughput and low-power.

The GNSS scanner of the LR1120 has two modes of operations: autonomous and assisted.

#### **4.1.2.1 Autonomous GNSS Scanning**

The LR1120 will not require any assistance information in this mode. A fast search of all SVs with strong signals in the selected constellation is performed, and all the SVs received with a signal better than RXSGPS1E are detected. This mode can be used to determine if the device stands indoor or outdoor; in case no SV with strong signal is detected, the application concludes that the device is indoor. Therefore the search of weak signals, which is more time and energy consuming, can be discarded; the search of other signals of opportunity, like Wi-Fi, might be launched instead.

#### **4.1.2.2 Assisted GNSS Scanning**

Based on the assistance information, the LR1120 will build a list of 10 to12 SVs that it should look for at the position of the device and the actual time.

Two different assisted GNSS scanning modes are implemented:

- **•** "Low power": A first search of strong signal satellites within the list of visible ones will be made. If at least one satellite is found in this step, the search will continue for satellites with weaker signals. Otherwise the search will stop. This mode minimizes the energy consumption and can also be used also as indoor/ outdoor detection method, in a more efficient way than the autonomous GNSS scanning mode. The indoor classification is decided after searching 10-12 SVs, versus 32-35 in Autonomous scanning mode.
- **•** "Best effort": A first search of SVs with strong signals, within the list of visible satellites, is made. Even if no satellite is found in the first phase, the search continues for satellites with weaker signals. This mode is to be used in difficult environments where is may be possible to find SVs, at the expense of a longer search phase.

The scanner uses a sequence of capture and processing phases. To preserve power, the RF front-end will be turned off during the processing phases.

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#### **4.1.2.3 GNSS Geolocation System Overview**

The LR1120 features a GNSS receiver that allows a fast and energy efficient outdoor geolocation. This GNSS Geolocation System achieves low energy geolocation by offloading time- and compute- intensive operations to back-end system components. In particular, the LR1120's GNSS Geolocation System uses the following three back-end system components:

- **•** GNSS Position Solving Component: the LR1120 does not resolve the full position on-device. Instead, the measurements from GNSS signals are combined into a binary message (the NAV message) and expected to be sent via any communication channel to the GNSS Position Solver backend component for final position calculation. This component is required in all operation modes.
- **•** GNSS Almanac Update Component (required in assisted mode): the LR1120 is able to reduce the GNSS scanning time by taking into account coarse orbital parameters for different GNSS constellations (the Almanac parameters). In conjunction with a coarse time and position estimate, the LR1120 uses this information to optimize the search an acquisition of GNSS signals. Over time, the true satellite positions diverge from the fixed Almanac parameters, which requires them to be updated. This can be achieved by a back-end component which estimates the quality of the almanac image on device and issues updates when needed. This component is required if GNSS assisted mode is used.
- **•** GNSS Assistance Component (required in assisted mode): in order to operate GNSS Geolocation System in assisted mode, coarse estimates of time and position must be provided to the LR1120. This information can be obtained in a variety of ways including application-level knowledge. In LoRaWAN the Clock Synchronization protocol can retrieve assistance time information. The assistance position information can generally be derived from past position solutions.

[LoRa Cloud™ offers these components in a single, easy to use, managed service as part of the Modem & Geolocation](http://www.loracloud.com) [Services. Visit](http://www.loracloud.com) [www.loracloud.com for more information.](www.loracloud.com)

## <span id="page-28-0"></span>**4.2 LR-FHSS Modulation**

The LR1120 supports LR-FHSS modulation (compliant with the LoRaWAN™ specification released by the LoRa Alliance™), which modulates the packet content across several pseudo-random frequencies, providing the following benefits:

- **•** In FCC regions, the LR-FHSS can eliminate the dwell-time limitation by intra-packet hopping. It thus allows to use slower data rates, which increases the communication range, and to carry a longer payload.
- **•** In ETSI regions, the LR-FHSS can provide improved capacity and an even longer range than LoRa for lower data rate devices where the spectrum is limited such as Europe or India.
- **•** The LR-FHSS modulation provides even better robustness in the presence of interferences than LoRa.

The LR1120 is able to generate LR-FHSS modulated packets on sub-GHz and 2.4 GHz ISM bands.

LR-FHSS implementation in the LR1120 is transmit only.

## <span id="page-28-1"></span>**4.3 Exiting Sleep Mode**

The LR1120 exits the lowest-power Sleep mode with:

- **•** A falling edge on the NSS signal
- **•** A RTC Timeout configured in the SetSleep() command, as an option

Implementation options are detailed in the User Manual, and both can be combined.

# <span id="page-29-0"></span>**4.4 Digital Inputs/Outputs**

The LR1120 features 12 DIO pins, dedicated to host or sensors/peripherals communication, interruption handling and external RF switches or LNA control.

## <span id="page-29-1"></span>**4.4.1 DIO Configuration**

The LR1120 features a DIO switch matrix (SWM), allowing a reconfiguration of the DIOs depending on the application requirements. For a transceiver use case, the LR1120 is controlled by a host MCU, hence the DIOs are dedicated to host communication. In order to reduce the constraints on the MCU pin count, five DIOs can be used to control external RF switches or LNAs.

#### **Table 4-1: LR1120 DIO Mapping**



## <span id="page-29-2"></span>**4.4.2 RF Switch Control**

The LR1120 is able to control up to 5 external RF switches or LNAs on the RFIO\_HF, GNSS, and Sub‐GHz RF paths, reducing the number of host controller IOs required for the application. This allows selecting application MCUs with a reduced pin count or a smaller footprint, and therefore designing highly integrated solutions. The polarity of the RF switch control signals can be set in each radio mode. By default no DIO is used as RF switch control line, all RF switch outputs are kept in High-Z state.

## <span id="page-29-3"></span>**4.4.3 Reset**

A complete restart of the LR1120 internal firmware can be issued on request by toggling the NRESET pin. It will be automatically followed by the standard calibration procedure and any previous context will be lost. The pin should be held low for more than 100 μs for the reset to occur.

## <span id="page-30-0"></span>**4.4.4 Host Interrupts**

The LR1120 offers 24 interrupt sources, allowing the host to react to special events in the LR1120 system without the need to poll registers, in order to design power optimized applications.

Interrupts to the host are signalled through one (or more) IRQ lines configured on the DIOs, and can be masked or cleared using dedicated commands.

The interrupt status can be read by the host through the 32-bit interrupt status register. They can be cleared by writing a 1 to the respective bit.

# <span id="page-30-1"></span>**4.5 Firmware Upgrade/ Update**

During the manufacturing process, the LR1120 will be provisioned and contain the embedded firmware image. During the product assembly process, the customer will be able to upgrade the full embedded firmware image running on the LR1120 via the SPI interface. The bootloader of the LR1120 will authenticate the firmware and will allow further execution. Only firmware images provided by Semtech can run on the LR1120. The LR1120 can also support patch updates, typically for maintenance in the field.

# <span id="page-31-0"></span>**4.6 Simplified Reference Schematic**

This section provides reference schematic examples using the LR1120.

#### **Figure 4-4: Multi-band EU/US LoRaWAN Using Both sub-GHz PAs + GNSS + Wi-Fi Passive Scanner**



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A 32 MHz TCXO is mandatory for GNSS scan.

For products that only perform Wi-Fi scans, the TCXO can be replaced by an XTAL, between pin 4 and pin 5.

An external LNA is required on the GNSS receive path for GNSS scanning. The LNA is controlled using the RFSWx signals.

A 32.768 kHz clock source is necessary for the GNSS Advanced scan and dual constellation scans.

# <span id="page-32-0"></span>**4.7 Example Reference Layout**

**Figure 4-5: Reference Design Layout** 

![](_page_32_Figure_2.jpeg)

# <span id="page-33-0"></span>**5. Package Information**

# <span id="page-33-1"></span>**5.1 Package Outline Drawing**

#### **Figure 5-1: Package Outline Drawing**

![](_page_33_Figure_3.jpeg)

![](_page_33_Picture_124.jpeg)

1. CONTROLLING DIMENSIONS ARE IN MILLIMETERS (ANGLES IN DEGREES).

2. COPLANARITY APPLIES TO THE EXPOSED PAD AS WELL AS THE TERMINALS.

<u>ທ</u> **e m t e c h C o n fid e n tial**

# <span id="page-34-0"></span>**5.2 Package Marking**

**Figure 5-2: Package Marking**

![](_page_34_Picture_2.jpeg)

![](_page_34_Picture_102.jpeg)

Marking for the 5 x 5 mm MLPQ 32 Lead package:

nnnnnn = Part Number (Example: LR1120) yyww = Date Code (Example: 2052) xxxxxx = Semtech Lot No (Example: E90101 xxxxxx  $0101 - 1)$ 

## <span id="page-35-0"></span>**5.3 Land Pattern**

**Figure 5-3: Land Pattern**

![](_page_35_Figure_2.jpeg)

![](_page_35_Picture_155.jpeg)

NOTES:

- 1. THIS LAND PATTERN IS FOR REFERENCE PURPOSES ONLY. CONSULT YOUR MANUFACTURING GROUP TO ENSURE YOUR COMPANY'S MANUFACTURING GUIDELINES ARE MET.
- 2. THERMAL VIAS IN THE LAND PATTERN OF THE EXPOSED PAD SHALL BE CONNECTED TO A SYSTEM GROUND PLANE. FAILURE TO DO SO MAY COMPROMISE THE THERMAL AND/OR FUNCTIONAL PERFORMANCE OF THE DEVICE.
- 3. SQUARE PACKAGE DIMENSIONS APPLY IN BOTH "X" AND "Y" DIRECTIONS.

# <span id="page-35-1"></span>**5.4 Reflow Profiles**

Reflow process instructions are available from the Semtech website, at the following address: http://www.semtech.com/quality/ir\_reflow\_profiles.html

The device uses a QFN32 5x5 mm package, also named MLP package.

# <span id="page-35-2"></span>**5.5 Thermal Information**

#### **Table 5-1: Package Thermal Information**

![](_page_35_Picture_156.jpeg)

1. As measured on a 4-layer test board with 9 thermal vias, per the Jedec standard

# **Glossary**

## **List of Acronyms and their Meaning (Sheet 1 of 3)**

![](_page_36_Picture_231.jpeg)

## **List of Acronyms and their Meaning (Sheet 2 of 3)**

![](_page_37_Picture_240.jpeg)

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## **List of Acronyms and their Meaning (Sheet 3 of 3)**

![](_page_38_Picture_107.jpeg)

![](_page_39_Picture_0.jpeg)

![](_page_39_Picture_1.jpeg)

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